

## Efficiency Analysis of Queueing Model Validation by Use of Trace-Driven Simulation

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Validation of queueing models is the main practical task. *The Trace-driven simulation* approach is often used for this purpose (Kleijnen et al. 1999, Andronov 2000, 2001). This approach can be described in the following way. We suppose that a real queueing system of interest has an observed input  $A_1, A_2, \dots, A_n$  and an observed output or replicate  $W_1, W_2, \dots, W_n$ . For example,  $A_1, A_2, \dots, A_n$  form a sequence of arrival times of customers into a queueing system,  $W_1, W_2, \dots, W_n$  form a sequence of sojourn times of the customers in the system or the output times from the system. The output series are evaluated through a performance measure (response)  $X$ , the average sojourn time of the customers, for example.

We have a theoretical queueing model as well. We should verify its adequacy to the real system, it is the so-called *null-hypothesis*. For this purpose we use the same *trace*  $\mathbf{A} = (A_1, A_2, \dots, A_n)$  and produce the simulation  $R$  times. As a result we get  $R$  simulated outputs (replicates)  $\tilde{W}_1^{(r)}, \tilde{W}_2^{(r)}, \dots, \tilde{W}_n^{(r)}$ , where  $r$  is a run number of the simulation,  $r = 1, 2, \dots, R$ . Let  $\tilde{X}^{(1)}, \tilde{X}^{(2)}, \dots, \tilde{X}^{(R)}$  be a corresponding sequence of the performances (responses).

To validate the theoretical model (to test the null-hypothesis), the real and simulated performances  $X$  and  $\tilde{X}^{(1)}, \tilde{X}^{(2)}, \dots, \tilde{X}^{(R)}$  should be compared statistically. Some solutions of this problem were given in (Kleijnen et al. 1999). We consider another approach. The simplest way supposes a sorting of the simulated performances  $\tilde{X}^{(1)}, \tilde{X}^{(2)}, \dots, \tilde{X}^{(R)}$ . It gives the order statistics  $\tilde{X}_{(1)}, \tilde{X}_{(2)}, \dots, \tilde{X}_{(R)}$  and the estimated  $\alpha$ -quantile of the distribution  $\tilde{X}_{(\lfloor R\alpha \rfloor)}$ . This procedure gives, for example, a two-sided  $(1 - \alpha)$ -confidence interval for the original value  $X$ , ranging from the lower estimated  $\alpha/2$ -quintile to the upper  $(1 - \alpha/2)$ -quintile. If  $X$  value falls outside this interval then we reject the theoretical model (the null-hypothesis). In addition, the significance level of this testing is equal to  $\alpha$ .

Our aim is to investigate the efficiency of the described approach for a quite general case of queueing system. We shall consider these systems as a composite two-component embedded Semi-Markov process. Here the input of the queueing system  $\mathbf{A}$  corresponds to a Semi-Markov process  $A(t)$ . The latter is described by a discrete set  $\Omega_A$  of states, matrix of one-step transition probabilities  $\mathbf{P} = (P_{i,j})$  and the distribution function  $F_i(t)$  of sojourn time in each state  $i \in \Omega_A$ . Obviously,

$$\sum_{j \in \Omega_A} P_{i,j} = 1, \quad F_i(\infty) = 1, \quad \forall i \in \Omega_A.$$

Remind (Ross, 1992, p.86) that "Semi-Markov process records the state of the process at each time point  $t$ ". So we have these states as the considered input  $\mathbf{A} = (A_1, A_2, \dots, A_n)$ .

Further we suppose that the inner structure of our queueing system is described by a stochastic process  $S(t)$  with a discrete set of states  $\Omega_S$ . If the state  $J \in \Omega_A$  of the Semi-Markov process  $A(t)$  takes place then the process  $S(t)$  behaves as an independent Semi-Markov process with the matrix  $\mathbf{P}^{S,J}$  of one-step

transition probabilities and the distribution function  $F_i^{S,J}(\cdot)$  of sojourn time in the state  $i \in \Omega_S$ . We shall name jumps (transitions) of the process  $A(t)$  as jumps of the first type and supplemental jumps of the process  $S(t)$  only as the jumps of the second type. Note that the probability to have a jump of the process  $\mathbf{A}(t)$  at a time  $t$  does not depend on the state of  $S(t)$ .

Let  $t^*$  be a time moment when a jump of the first type takes place,  $J_- = A(t^*-)$  and  $J_+ = A(t^*+)$  be the states of the process  $A(t)$  immediately before and after this time moment. Let  $J_-^S = S(t^*-)$  and  $J_+^S = S(t^*+)$  be the same for the process  $S(t)$ . If  $J_+$  is entered, the next state  $J_+^S$  of the process  $S(t)$  is chosen according to the transition probabilities  $q_{J_-^S, J_+^S}^{J_-, J_+}$ . Then given that the state chosen is  $J_+^S$ , the time until transition of the process  $S(t)$  has the distribution function  $F_{J_+^S}^{S, J_+}(\cdot)$  as usually for  $S(t)$ .

Now we consider the sequence of time moments  $t_1, t_2, \dots$  when all jumps occur. Every one of such moments produces a random variable  $\tilde{W}$ , so  $\tilde{W}_1, \tilde{W}_2, \dots$  form the output of our system. To describe the corresponding stochastic mechanism, we introduce the following notations for the jump of the first type at the time moment  $t^*$ :  $\tau(t^*)$  - length of the interval between the previous and current jumps of the first type;  $U(t^*)$  - time till  $t^*$  since the last jump of the processes  $S(t)$ , so-called *age* of the current state at  $t^*$ . Then the probabilities  $Pr_1(J_-, J_+, J_-^S, J_+^S, \tau(t^*), U(t^*))$  to produce the random variables  $\tilde{W}$  are functions of  $J_-, J_+, J_-^S, J_+^S, \tau(t^*)$  and  $U(t^*)$ . For the jumps of the second type this probability is denoted by  $Pr_2(J, J_-^S, J_+^S, U(t^*))$ . If the corresponding random variable  $\tilde{W}$  will be produced, then its distribution function is given by the formulas

$$G_1^S(x; J_-, J_+, J_-^S, J_+^S, \tau(t^*), U(t^*)) = P\{\tilde{W} \leq x / J_-, J_+, J_-^S, J_+^S, \tau(t^*), U(t^*)\},$$

$$G_2^S(x; J, J_-^S, J_+^S, U(t^*)) = P\{\tilde{W} \leq x / J, J_-^S, J_+^S, U(t^*)\}.$$

The sequence  $\{\tilde{W}_i\}$  is an output from the simulated system with the inner structure, that is described by the process  $S(t)$ . Let the inner structure of the real system be described by the random process  $B(t)$ . We suppose that the process  $B(t)$  is similar to the process  $S(t)$  but may have some different parameters. Let  $W_1, W_2, \dots$  denote the output for the real process  $B(t)$  if the same input  $\mathbf{A}$  takes place. We must compare two sequences  $W_i$  and  $\tilde{W}_i$  statistically. For this purpose we use some performance measure  $X = \xi(W_1, W_2, \dots)$  and  $\tilde{X} = \xi(\tilde{W}_1, \tilde{W}_2, \dots)$ .

Let us calculate a conditional distribution function  $R_S(x/\mathbf{A})$  of  $\tilde{X}$  under the condition that the input (trace)  $\mathbf{A}$  is fixed, for example, by simulation:

$$R_S(x/\mathbf{A}) = P\{\tilde{X} \leq x/\mathbf{A}\}.$$

Let  $R_S^{-1}(\gamma/\mathbf{A})$  be the corresponding  $\gamma$ -quantile:  $R_S(R_S^{-1}(\gamma/\mathbf{A})/\mathbf{A}) = \gamma$ .

Now we are able to test the null hypothesis  $H_0$  that random processes  $B(t)$  and  $S(t)$  have the same probabilistic structure against the alternative hypothesis  $H_1$  that they are different. Let us suppose that if the alternative hypothesis  $H_1$  is true then the performance measure  $X$  is stochastically greater than  $\tilde{X}$ . In this case we reject the null-hypothesis for the significance level  $\alpha$  if the fixed value  $X$  exceeds  $R_S^{-1}(1 - \alpha/\mathbf{A})$ . In other words the decision interval for the null-hypothesis  $H_0$  is  $(0, R_S^{-1}(1 - \alpha/\mathbf{A}))$ . What is the *power function* for this test? We consider this problem in our paper.

## REFERENCES

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